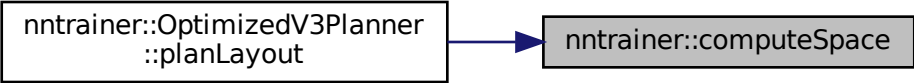


nntrainer::OptimizedV3Planner
::planLayout



```
graph LR; A[nntrainer::OptimizedV3Planner::planLayout] --> B[nntrainer::computeSpace];
```

nntrainer::computeSpace