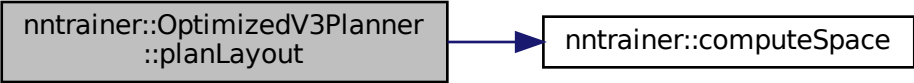


nntrainer::OptimizedV3Planner
::planLayout



```
graph LR; A["nntrainer::OptimizedV3Planner  
::planLayout"] --> B["nntrainer::computeSpace"]
```

nntrainer::computeSpace